

# lecture 22:

background on model checking

5590: software defined networking

anduo wang, Temple University

TTLMAN 401B, R 17:30-20:00

# Grand Challenge Problem: Model Check Concurrent Software



```
*p=3; x++; whi(7--){ f(1+
int mai(y); } x
<<16); whi(5); g=mp=(x
*p=*(x+ whi(4)); (<n 8
6); (y)x xp(xtm
((mp&8); mp=
((mp&16) int mai
); } xtm; } f){ l+
(FORALL i: j: ((n
& j>i) || (j<n && i== & j
a[i]<a[j]))); *p=3; ; wh
```

- Edmund M. Clarke
- Department of Computer Science
- Carnegie Mellon University

# Outline of Talk

1. Explain what model checking is
2. Some successes of model checking
3. What makes software different
4. Approaches to software model checking
5. Some of my projects

# Temporal Logic Model Checking

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- Developed independently by **Clarke, Emerson, and Sistla** and by **Queille and Sifakis** in early 1980's.
- **Specifications** are written in **propositional temporal logic**.
- Verification procedure is an **exhaustive search of the state space** of the design.



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- **No proofs!!!**
- **Fast (compared to other rigorous methods such as theorem proving)**
- **Diagnostic counterexamples**
- **No problem with partial specifications**
- **Logics can easily express many concurrency properties**

# Main Disadvantage

## State Explosion Problem:

- Too many processes
- Data Paths



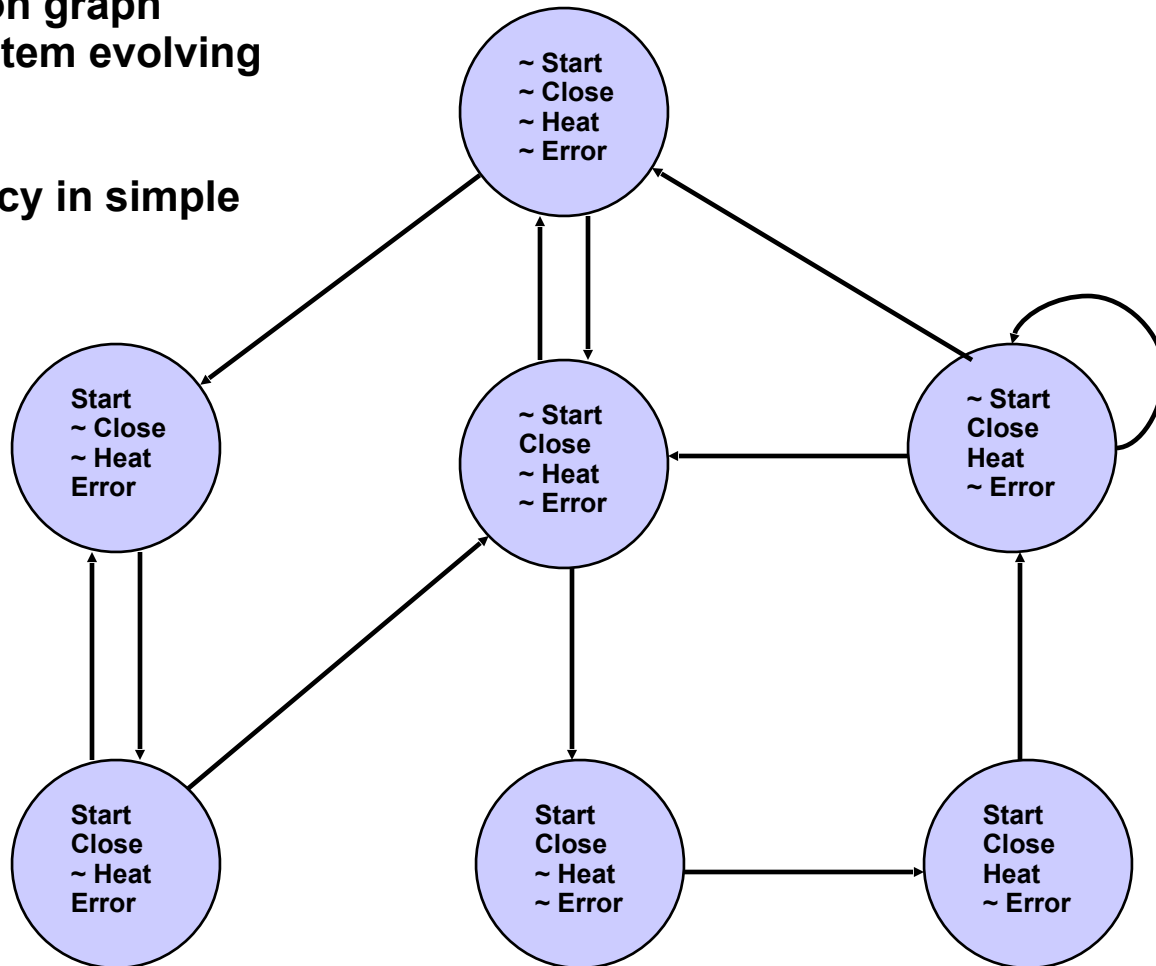
**Much progress has been made on this problem recently!**

# Model of computation

## Microwave Oven Example

State-transition graph describes system evolving over time.

No concurrency in simple examples.





# Temporal Logic



# Temporal Logic



- The oven doesn't **heat up** until the **door is closed**.

# Temporal Logic



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- The oven doesn't **heat up** until the **door is closed**.
- **Not heat\_up** holds **until door\_closed**
- $(\sim \text{heat\_up}) \text{ U } \text{door\_closed}$

# Basic Temporal Operators



The symbol “**p**” is an atomic proposition, e.g. “**Device Enabled**”.

- **F**p - p holds sometime in the *future*.
- **G**p - p holds *globally* in the future.
- **X**p - p holds *next* time.
- p**U**q - p holds *until* q holds.

# Model Checking Problem

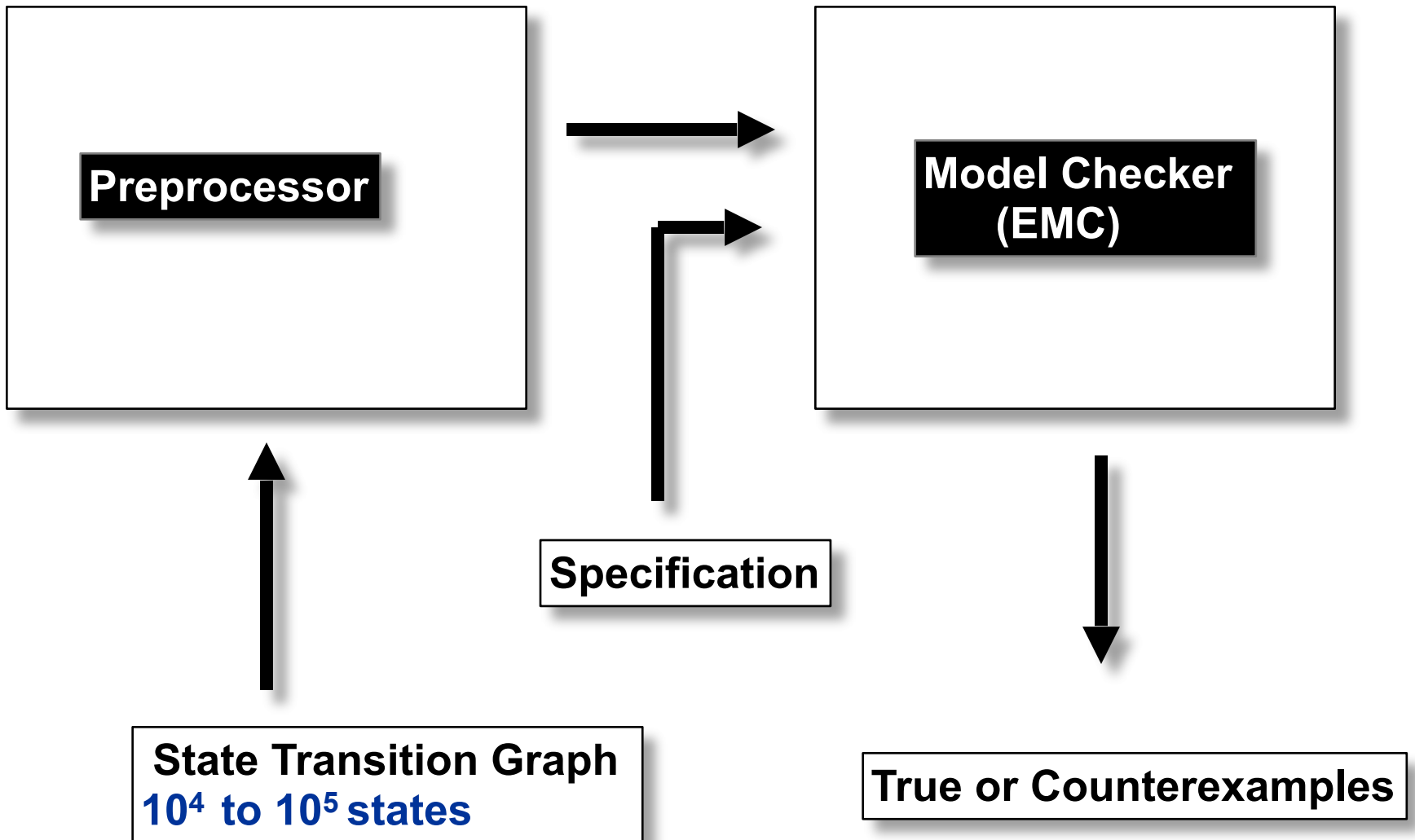
Let  $M$  be a **state-transition graph**.

Let  $f$  be the **specification** in temporal logic.

Find all states  $s$  of  $M$  such that  $M, s \models f$ .

Efficient Algorithms: CE81, CES83

# The EMC System



# Breakthrough!

Ken McMillan implemented our model checking algorithm using **Binary Decision Diagrams** in 1987.

Model Checker SMV

**Now able to handle much larger examples!!**



# Combating the State Explosion Problem

- **Binary Decision Diagrams** can be used to represent state transition systems more efficiently.
- The **partial order reduction** can be used to reduce the number of states that must be enumerated.
- Many techniques for alleviating state explosion:
  - **Abstraction.**
  - **Compositional reasoning.**
  - **Symmetry.**
  - **Cone of influence reduction.**
  - **Semantic minimization.**

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# Model Checker Performance

- Model checkers today can routinely handle systems with between **100** and **1000 state variables**.
- Systems with  **$10^{120}$  reachable states** have been checked. (Compare approx.  **$10^{78}$**  atoms in universe.)
- By using appropriate abstraction techniques, systems with an essentially **unlimited number of states** can be checked.

# Temporal Logic Model Checkers

- The first two model checkers were **EMC** (Clarke, Emerson, Sistla) and **Caesar** (Queille, Sifakis).
- **SMV** is the first model checker to use **BDDs**.
- **Spin** uses the **partial order reduction** to reduce the state explosion problem.
- **Verus** and **Kronos** check properties of **real-time systems**.
- **HyTech** is designed for reasoning about **hybrid systems**.

# Introduction to SMV

# Symbolic Model Verifier

- Ken McMillan, *Symbolic Model Checking: An Approach to the State Explosion Problem*, 1993.
- Finite-state Systems described in a specialized language
- Specifications given as CTL formulas
- Internal representation using OBDDs
- Automatically verifies specification or produces a counterexample

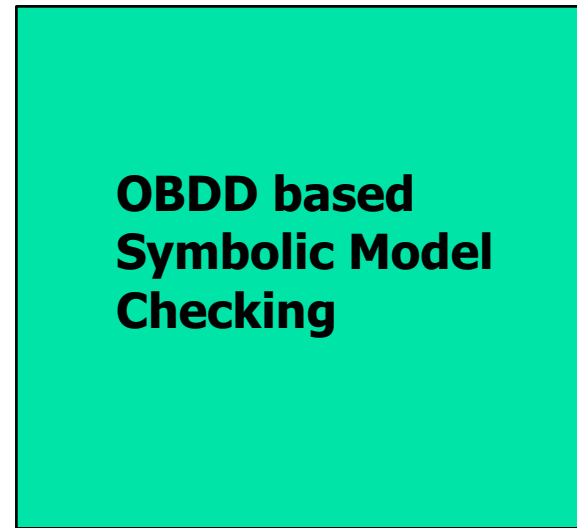


# Overview of SMV

**SMV Input  
Language**



**Backend**



Yes

No

**CounterExample**

# Kripke model

**Kripke model** A model of basic modal logic is specified by  $(W, R, L)$ , where:

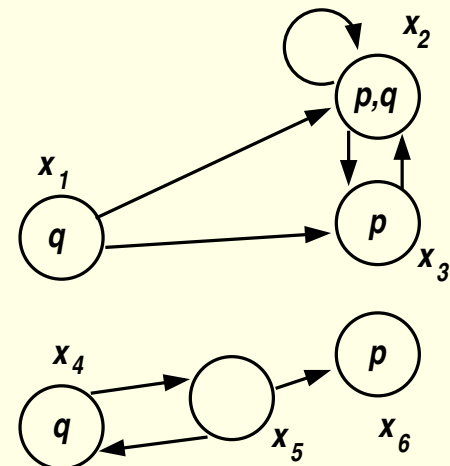
- $W$  is a set, whose elements are called worlds
- $R \subseteq W \times W$ : accessibility relation
- $L : W \rightarrow \mathcal{P}(\text{PropVar})$ : labeling function

## Example:

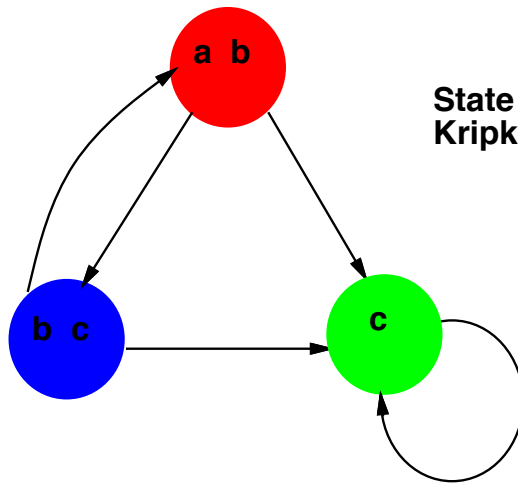
$$W = \{x_1, \dots, x_6\}$$

$$R = \{(x_1, x_2), (x_1, x_3), (x_2, x_2), (x_3, x_2), (x_4, x_5), (x_5, x_4), (x_5, x_6)\}$$

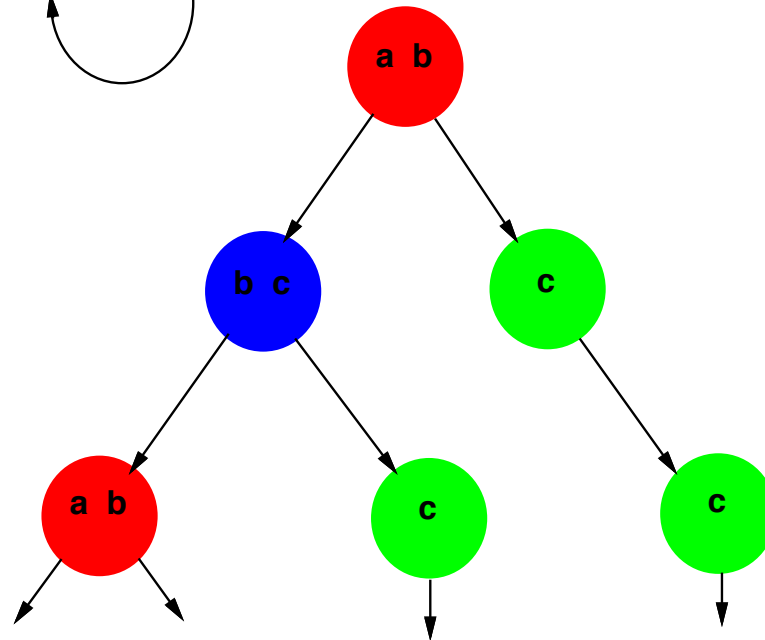
$x$	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$
$L(x)$	$\{q\}$	$\{p, q\}$	$\{p\}$	$\{q\}$	$\emptyset$	$\{p\}$



# Kripke model and computation tree



State Transition Graph or Kripke Model



Infinite Computation Tree

# computation tree logic (CTL)

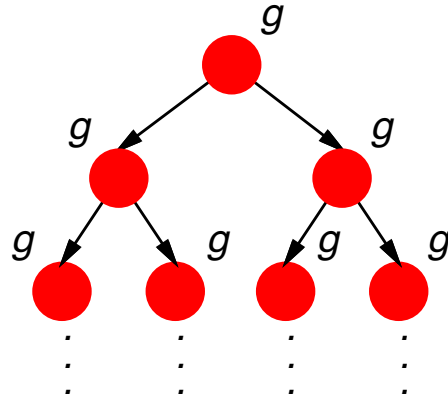
## 1. Path quantifier:

- **A**—“for every path”
- **E**—“there exists a path”

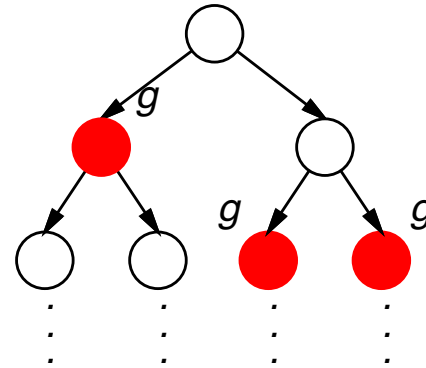
## 2. Linear-time operators:

- **X** $p$ — $p$  holds **next** time.
- **F** $p$ — $p$  holds sometime in the **future**
- **G** $p$ — $p$  holds **globally** in the future
- $p$ **U** $q$ — $p$  holds **until**  $q$  holds

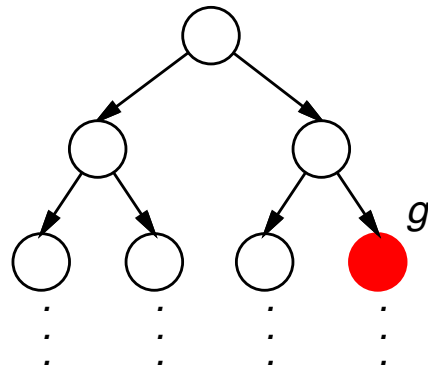
# CTL formula



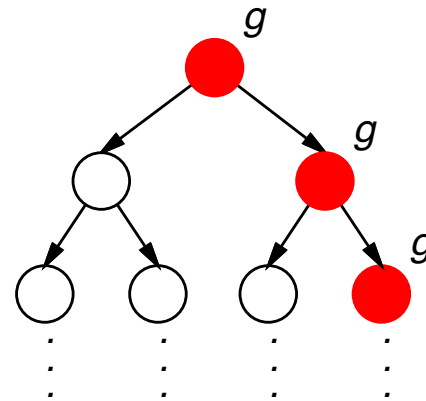
$M, s_0 \models \mathbf{AG} g$



$M, s_0 \models \mathbf{AF} g$



$M, s_0 \models \mathbf{EF} g$



$M, s_0 \models \mathbf{EG} g$

# typical CTL formula

- **EF**(*Started*  $\wedge$   $\neg$ *Ready*): it is possible to get to a state where *Started* holds but *Ready* does not hold.
- **AG**(*Req*  $\Rightarrow$  **AF***Ack*): if a *Request* occurs, then it will be eventually *Acknowledged*.
- **AG**(**AF** *DeviceEnabled*): *DeviceEnabled* holds infinitely often on every computation path.
- **AG**(**EF** *Restart*): from any state it is possible to get to the *Restart* state.

# SMV Language Characteristics

- Allows description of completely synchronous to asynchronous systems, detailed to abstract systems
- Modularized and hierarchical descriptions
- Finite data types: Boolean and enumerated

# The first SMV Program

```
MODULE main
```

```
VAR
```

```
    request: boolean;
```

```
    state: {ready, busy};
```

```
ASSIGN
```

```
    init(state) := ready;
```

```
    next(state) :=
```

```
        case
```

```
            state=ready & request: busy;
```

```
            1: {ready, busy};
```

```
        esac;
```

```
SPEC AG(request -> AF (state = busy))
```



# Modularization

```
DEFINE
```

```
  a := 0;
```

```
VAR
```

```
  b : bar(a);
```

```
...
```

```
MODULE bar(x)
```

```
  DEFINE
```

```
    a := 1;
```

```
    y := x;
```

# Modularization

...

VAR

a : boolean;

b : foo(a);

...

MODULE foo(x)

ASSIGN

x:=1;

# Asynchronous Composition

MODULE main

VAR

gate1: process inverter(gate3.output);

gate2: process inverter(gate1.output);

gate3: process inverter(gate2.output);

SPEC

(AG AF gate1.output) & (AG AF !gate1.output)

MODULE inverter(input)

VAR output: boolean;

ASSIGN

init(output) := 0;

next(output) := !input;

# Fairness

- **FAIRNESS** ctl\_formulae
  - Assumed to be true infinitely often
  - Model checker only explores paths satisfying fairness constraint
  - Each fairness constraint must be true infinitely often
- If there are no fair paths
  - All existential formulas are false
  - All universal formulas are true
- **FAIRNESS** running

# With Fairness..

```
MODULE main
```

```
VAR
```

```
  gate1: process inverter(gate3.output);
```

```
  gate2: process inverter(gate1.output);
```

```
  gate3: process inverter(gate2.output);
```

```
SPEC
```

```
(AG AF gate1.output) & (AG AF !gate1.output)
```

```
MODULE inverter(input)
```

```
VAR  output: boolean;
```

```
ASSIGN
```

```
  init(output) := 0;
```

```
  next(output) := !input;
```

```
FAIRNESS
```

```
  running
```

# Shared Data Example

Two Users assign pid to shared data in turn

MODULE main

VAR

data : boolean;

turn : boolean;

user0 : user(0, data, turn);

user1 : user(1, data, turn);

ASSIGN

next(turn) := !turn;

SPEC

AG (AF data & AF (!data))

# Shared data example (cont..)

```
MODULE user(pid, data, turn)
```

```
ASSIGN
```

```
  next(data) := case
```

```
    turn: pid;
```

```
    1 : data;
```

```
  esac;
```

# Run SMV

- `smv [options] inputfile`
  - `-c` cache-size for BDD operations
  - `-k` key-table-size for BDD nodes
  - `-v` verbose
  - `-int` interactive mode
  - `-r`
    - prints out statistics about reachable state space



# Example: Client & Server

```
MODULE client (ack)
```

```
VAR
```

```
  state : {idle, requesting};
```

```
  req : boolean;
```

```
ASSIGN
```

```
  init(state) := idle;
```

```
  next(state) :=
```

```
    case
```

```
      state=idle : {idle, requesting};
```

```
      state=requesting & ack : {idle, requesting};
```

```
      1 : state;
```

```
    esac;
```

```
  req := (state=requesting);
```

```
MODULE server (req)
```

```
VAR
```

```
  state : {idle, pending, acking};  
  ack : boolean;
```

```
ASSIGN
```

```
  next(state) :=  
  case  
    state=idle & req : pending;  
    state=pending : {pending, acking};  
    state=acking & req : pending;  
    state=acking & !req : idle;  
  1 : state;  
  esac;
```

```
  ack := (state = acking);
```

# Is the specification true?

MODULE main

VAR

c : client(s.ack);

s : server(c.req);

SPEC AG (c.req  $\rightarrow$  AF s.ack)

- Need fairness constraint:
  - Solution:  
FAIRNESS (c.req  $\rightarrow$  s.ack)

# NuSMV

- Specifications expressible in CTL, LTL and Real time CTL logics
- Provides both BDD and SAT based model checking.
- Uses a number of heuristics for achieving efficiency and control state explosion
- Higher number of features in interactive mode