

WHETHER AND WHEN TO SHARE: SPECTRUM SENSING AS AN EVOLUTIONARY GAME

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CONCLUSION

- Spectrum sensing is the key phase to identifying the spectrum availability in cognitive radio networks (CRNs).

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 - Protect the active primary users.

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- The fundamental task of spectrum sensing contains two aspects:
 - Protect the active primary users.
 - Detect the available channels.

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- Spectrum sensing is the key phase to identifying the spectrum availability in cognitive radio networks (CRNs).
- The fundamental task of spectrum sensing contains two aspects:
 - Protect the active primary users.
 - Detect the available channels.
- The objectives of secondary users are to maximize the utilization of the available spectrum and to prevent interference with primary users.

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- How to measure the performance of spectrum sensing:

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- How to measure the performance of spectrum sensing:
 - Probability of detection: the probability of a secondary user detecting a primary user when the spectrum is occupied by the primary user;
 - Probability of false alarm: the probability of a secondary user falsely declaring a primary user as present, when it is actually not occupied.

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- How to measure the performance of spectrum sensing:
 - Probability of detection: the probability of a secondary user detecting a primary user when the spectrum is occupied by the primary user;
 - Probability of false alarm: the probability of a secondary user falsely declaring a primary user as present, when it is actually not occupied.
- To ensure the spectrum sensing quality, adequate sample collection is required over a period of time for analysis by secondary users.

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- However, the time spent by the secondary user on spectrum sensing will reduce the time spent on data transmission.

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- For each secondary user, there is a tradeoff between the time used for spectrum sensing and the time used for data transmission.

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- However, the time spent by the secondary user on spectrum sensing will reduce the time spent on data transmission.
- For each secondary user, there is a tradeoff between the time used for spectrum sensing and the time used for data transmission.
- One effective approach to solve this is cooperative sensing.

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- Many works apply game theory on cooperative spectrum sensing.
 - They determine the relative probability of a secondary user participating.
 - The strategy set is usually {contribute, not contribute}.

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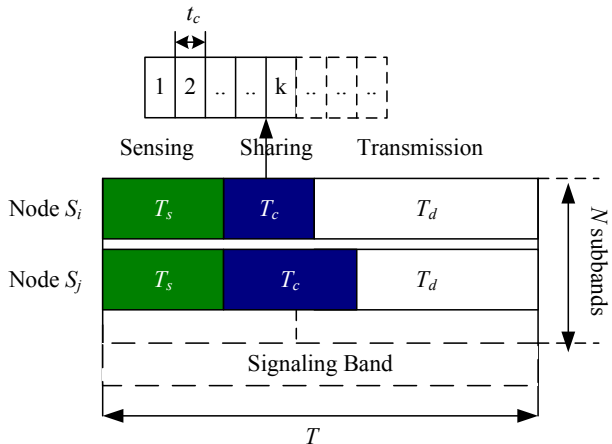
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- Many works apply game theory on cooperative spectrum sensing.
 - They determine the relative probability of a secondary user participating.
 - The strategy set is usually {contribute, not contribute}.
- We consider an extended strategy set, including “when to share” .

SYSTEM MODEL

Each time slot is divided into three parts.



SYSTEM MODEL

- Suppose the minimal time required for sending the sensing results when there is no conflict is t_c . Then T_c is divided into $\lceil \frac{T_c}{t_c} \rceil$ sub slots.

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SYSTEM MODEL

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- For a certain SU, it can choose whether to share its sensing results or not. If a node decides not to share its sensing results, its sharing time length would be 0.
- If it chooses to cooperate with others, it needs to choose one sub slot of T_c to send the sensing results.
 - The sensing results are confirmed to be received successfully through the ACKs. The sharing phase of a node ends as long as one ACK is received.
 - Before that, the current secondary user keeps listening to the signaling channel for others' sensing results.

OBJECTIVE & CONSTRAINTS

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- The constraints here are the requirements of the performance of spectrum sensing.
 - Both the probability of detection and probability of false alarm have to meet the required threshold.

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- The constraints here are the requirements of the performance of spectrum sensing.
 - Both the probability of detection and probability of false alarm have to meet the required threshold.
- The objective is defined based on each secondary user's view, which is to maximize its own utility.
 - The utility is related to the throughput of the secondary user considering both active and inactive status of primary users.

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- We build the evolutionary game for our model.
 - The key insight is that many behaviors involve the interactions of multiple strategies of different players, and the success of any strategy depends on how it interacts with others.

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- We build the evolutionary game for our model.
 - The key insight is that many behaviors involve the interactions of multiple strategies of different players, and the success of any strategy depends on how it interacts with others.
- The objective is to find the evolutionarily stable strategy (ESS), which tends to persist once it is adopted by most players.
 - Due to dynamics in the spectrum availability in CRNs, there is not a static stable strategy for each user conducting spectrum sensing.

GAME MODEL

- The secondary users in our model consider both whether and when to share their sensing results.

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- The secondary users in our model consider both whether and when to share their sensing results.
- Based on this intuition, we have the definition of the strategy set for our model.
 - The strategy set of an SU is $\{(C, j)\}$, where $j \in \{0, 1, \dots, \lceil \frac{T_c}{t_c} \rceil\}$. $j = 0$ means the SU denies to share its sensing results. Otherwise, the SU sends its sensing results at the j th sub slot of T_c .

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- The payoff of each secondary user is defined based on the throughput after it adopts one strategy.

GAME MODEL

- We prove the existence of ESS in our game model and give the replicator dynamics that can have a secondary user converge to the ESS.

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- We prove the existence of ESS in our game model and give the replicator dynamics that can have a secondary user converge to the ESS.
- The algorithm for each secondary user is basically to adjust its strategy based on its payoff and the replicator dynamics.

Algorithm 1 Evolutionary algorithm for S_i

1. $t_0 = 0, \forall (C, j), p_{(C,j)}(S_i) = p_0$
 2. $temp = 0$
 3. **while** NOT an ESS **do**
 4. $\tilde{t} = t_0$
 5. **while** $\tilde{t} < t_0 + \tilde{T}$ **do**
 6. Choose (C, j) with probability $p_{(C,j)}$
 7. Calculate $U_{(C,j)}(S_i)$ using Eq. 8
 8. $\tilde{t} = \tilde{t} + T$
 9. $t_0 = t_0 + 1$
 10. Calculate $\bar{U}_{(C,j)}(S_i)$ and $\bar{U}(S_i)$
 11. $\forall (C, j)$, update $p_{(C,j),S_i}$ using Eq. 13
 12. **if** $temp * (\bar{U}_{(C,j)}(S_i) - \bar{U}(S_i)) < 0$ **then**
 13. $\mu = \mu/2$
 14. $temp = \bar{U}_{(C,j)}(S_i) - \bar{U}(S_i)$
-

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- We use four USRPs to evaluate our model.
- Three USRPs simulate three secondary users. One USRP simulates the primary user.
- The three secondary users work on three subbands with different central frequencies: 1.3GHz, 1.30025GHz and 1.3005GHz.
- The primary user works on all three subbands at the same time.

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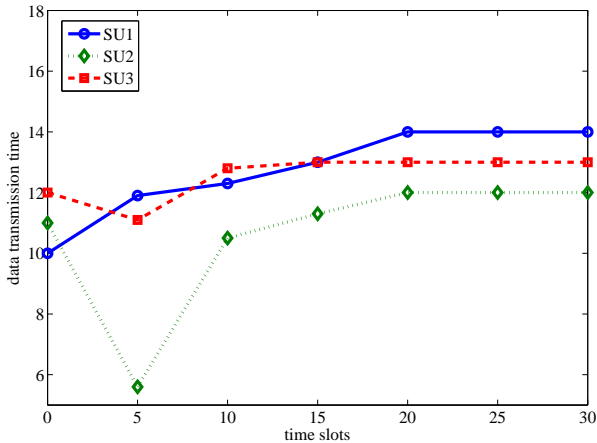
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Some other settings:

- The time slot length is 20s here (for better synchronization).
- The static sensing time is set to 5s, which is divided into 5 sub slots.
- The window size for each secondary to calculate the average throughput is 4 slots.
- The bandwidth of each secondary is 50k bps and the gain at each receiver is set to 20.

EXPERIMENT RESULTS

The experimental results of three secondary users:



CONCLUSION

- We consider both whether-to-share and when-to-share for the cooperative spectrum sensing in CRNs.
- We apply an evolutionary game model and define a novel strategy set for each player.
- We prove the existence of the evolutionary stable strategy (ESS) and provide a practical algorithm.
- We evaluate our model and the parameter influences through experiments.

Thank you!