

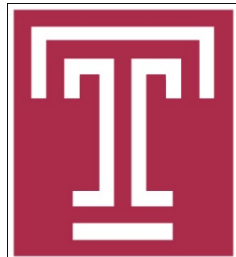
Optimizing Rebalance Scheme for Dock-less Bike Sharing Systems with Adaptive User Incentive

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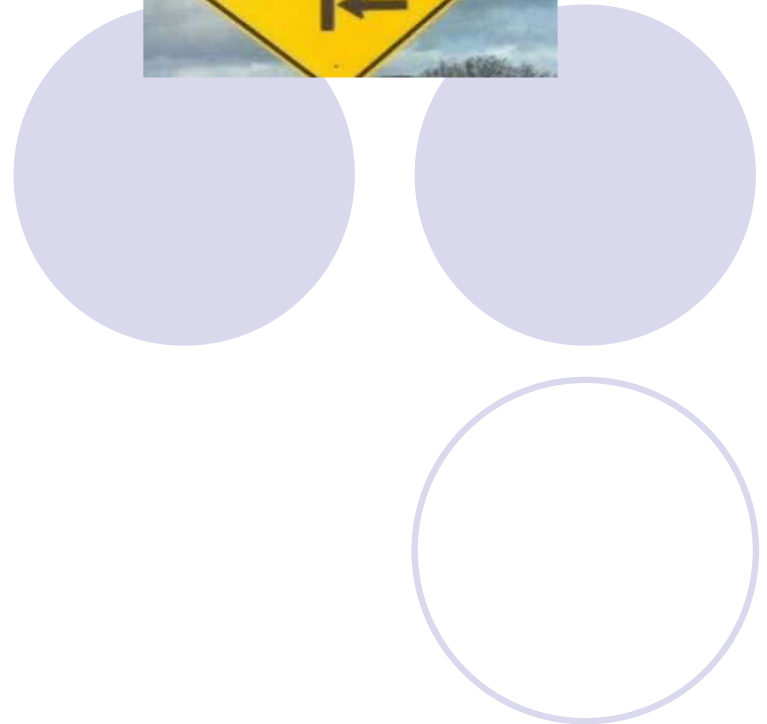
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Road Map

- Introduction
- Problem Formulation
- Algorithm Design
- Simulations
- Summary



1. Introduction

- Rebalancing dock-less bike sharing systems
 - underflow: an area lack of bikes, users cannot rent bikes
 - overflow: an area full of bikes, users cannot return bikes



- Existing incentive scheme: source detour
 - Incentivize users to rent bikes at alternative locations with detour

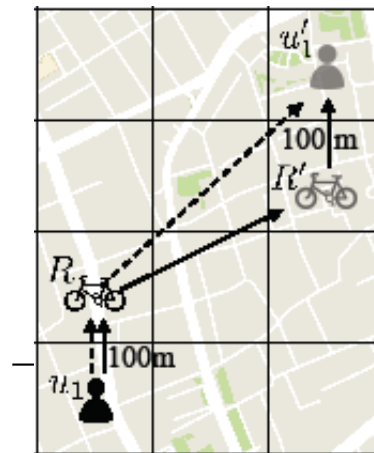
Motivation

- Destination detour

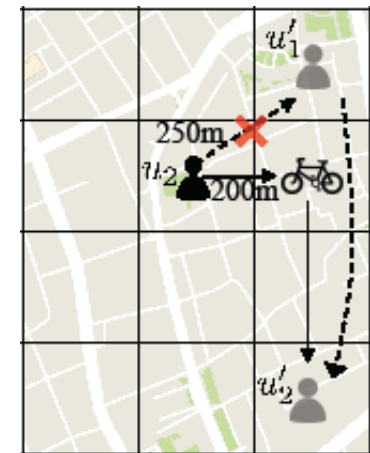
- A complement of source detour
- Example of destination incentive
 - temporal and spatial domains are discretized



user u_1 arrives with destination u_1'



offer source incentive only (dashed lines)
vs.
offer source and dest. Incentive (solid lines)



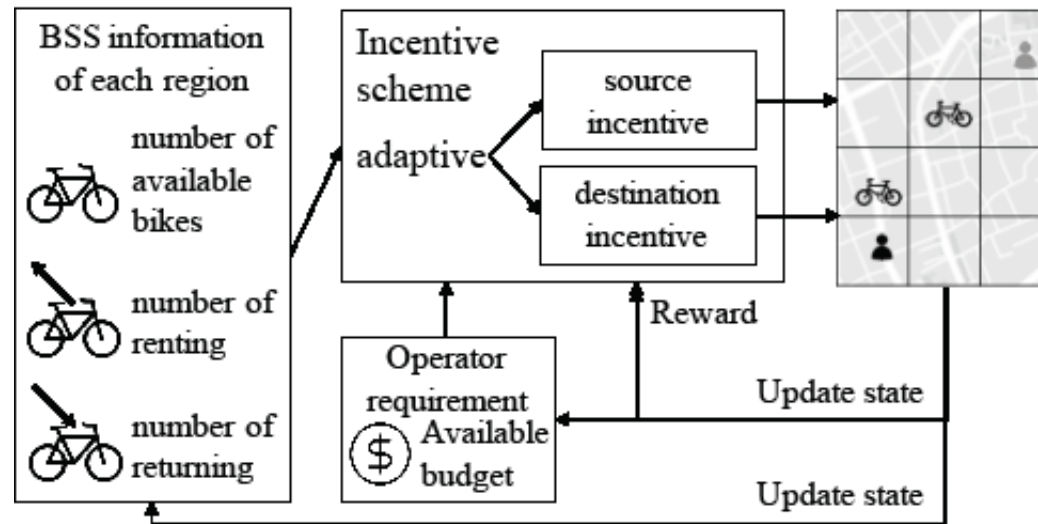
user u_2 arrives with destination u_2'

- Objective

- Maximize the total number of satisfied users over a day under a given budget

2. Model & Problem Formulation

- Rebalance scheme overview



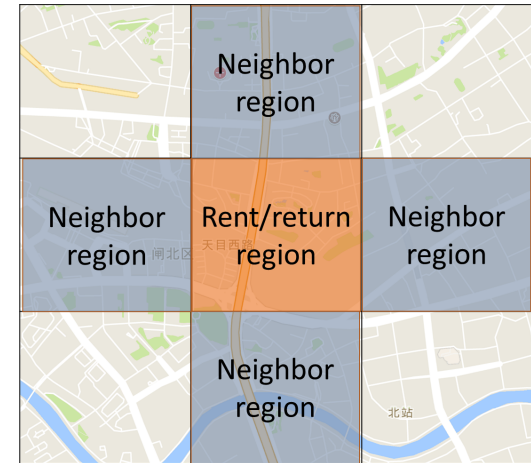
- System dynamic are modeled by Markov Decision Process (MDP)
 - state: supply $S(t)$, rent demand $D(t)$, arrival $A(t)$, and remaining budget $RB(t)$
 - action: source incentive price $P^+(t)$, and dest. incentive price $P^-(t)$
 - reward: number of satisfied requests (could successfully rent and return)

2. Model & Problem Formulation

- User model (Environment model)

- Cost of detour δ [2]

- 0 if the alternative renting or returning locations are in the same region
 - $C + \eta\delta^2$ if the alternative renting or returning locations are in neighbor regions
 - $+\infty$ otherwise



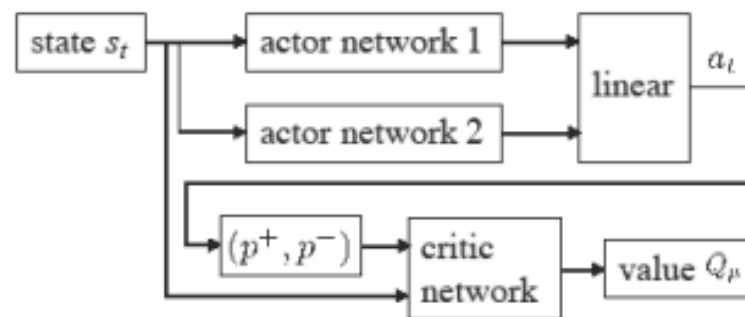
- A user accepts the incentive only if the incentive price is higher than the cost

- Problem formulation

max	$\sum_{t=1}^m \sum_{i,j=1}^n \tau_{ij}(t)$	(1) objective
s.t.	$\sum_{t=1}^m \sum_{i=1}^n p_i^+(t) < B - B^-$	(2) source incentive budget
	$\sum_{t=1}^m \sum_{i=1}^n p_i^-(t) \leq B^-$	(3) dest. incentive budget
	$\sum_{j=1}^n \tau_{ji}(t) - \sum_{j=1}^n \tau_{ij}(t) \leq \varphi_i(t), \forall i, t$	(4) inventory constraint
	$\varphi_i(t+1) = \varphi_i(t) + \sum_{j=1}^n (\tau_{ji}(t) - \tau_{ij}(t)) \forall i, t.$	(5) inventory evolution

3. Algorithm Design

- An existing solution for source incentive^[1]
 - Based on the deep deterministic policy gradients algorithm^[3]
 - They decompose the Q-value of the entire area of interest into multiple sub-Q-values of smaller regions.
- A hybrid incentive scheme
 - Considering both source and destination incentives
 - Extend the actor-critic framework used in [1]



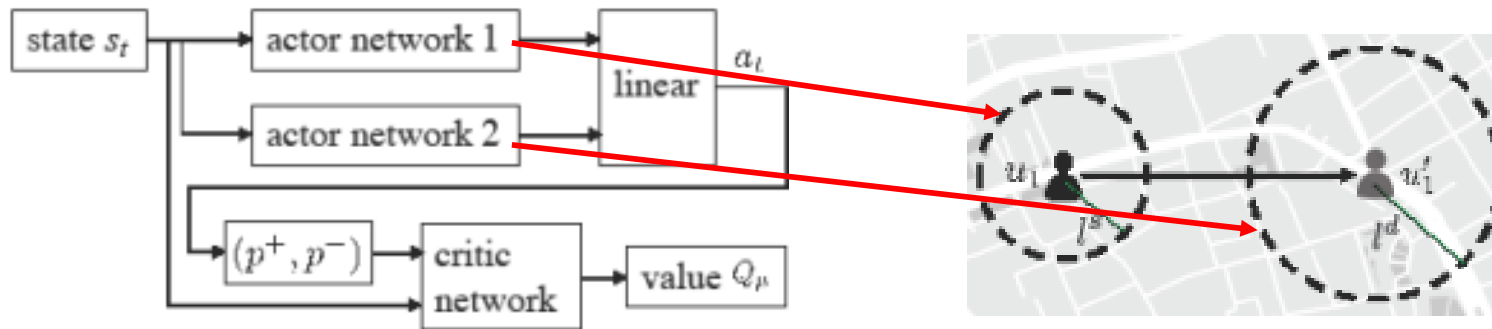
[1] A Deep Reinforcement Learning Framework for Rebalancing Dockless Bike Sharing Systems (AAAI '19)

[3] Continuous control with deep reinforcement learning (ICLR '16)

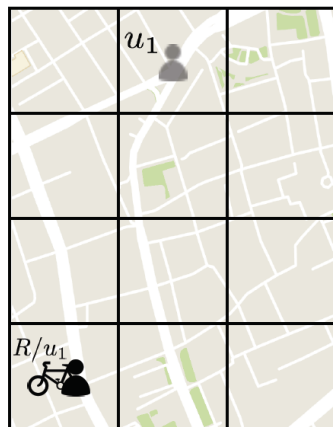
3. Algorithm Design

- Intuition of parameters in actor networks

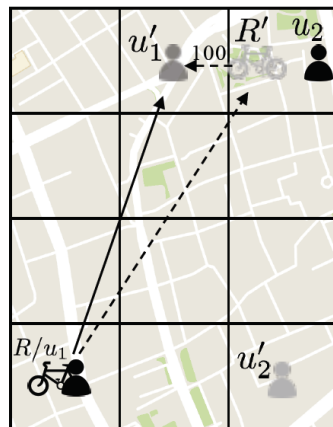
- Adaptively adjust the strength (the maximum detour distance) for source and destination incentives



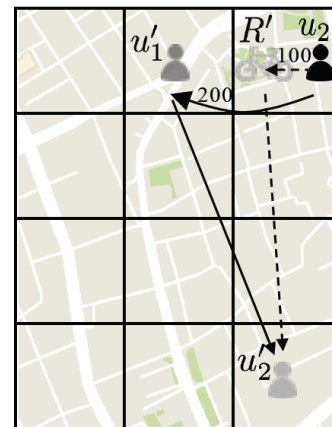
- Example: avoiding long-distance detour in our cost model ($\propto \delta^2$)



(a) $t=0$



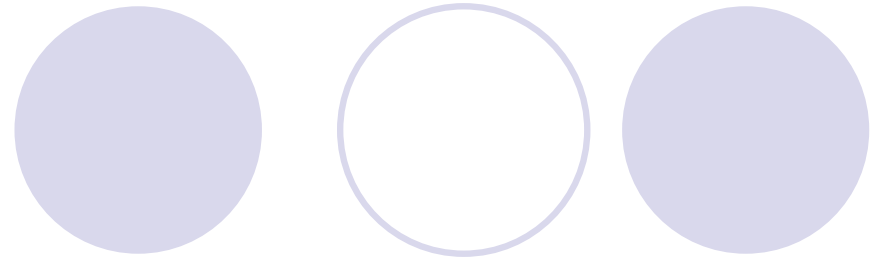
(b) $t=1$



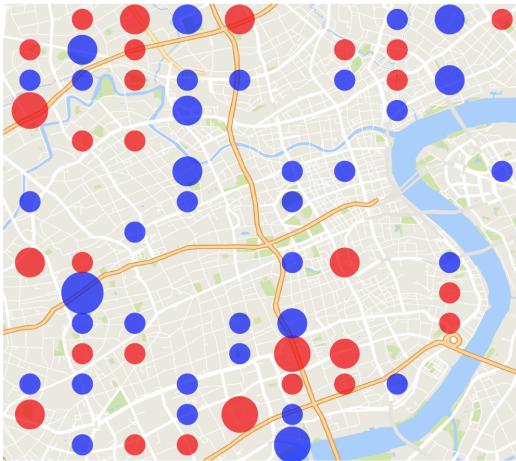
(c) $t=2$

solid lines: source incentive only
dashed lines: combining source and destination incentives
(two shorter detours)

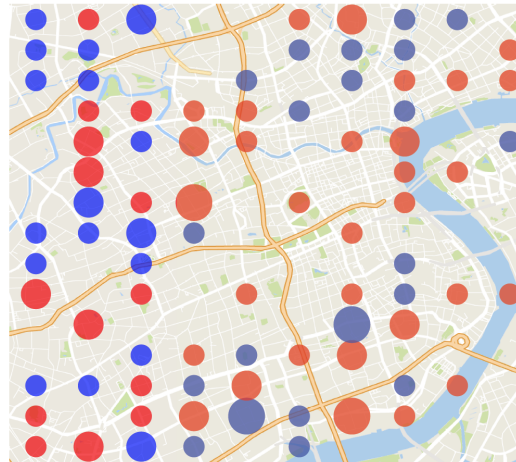
4. Simulations



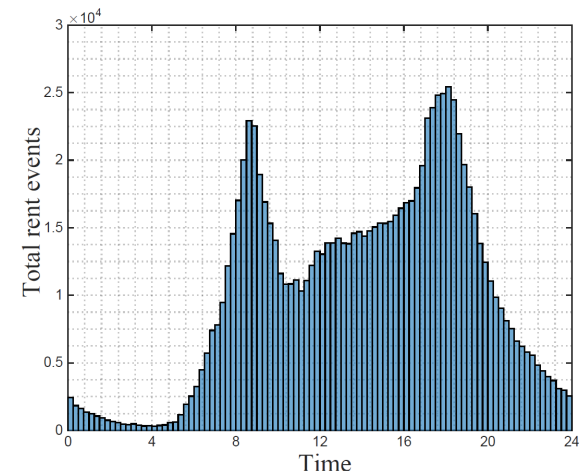
- Mobike dataset
 - One-month history trip data from 8/1/2016 to 9/1/2016 in Shanghai City
- Temporal and spatial imbalance distribution



Pick-up events in 8 a.m. – 9 a.m.



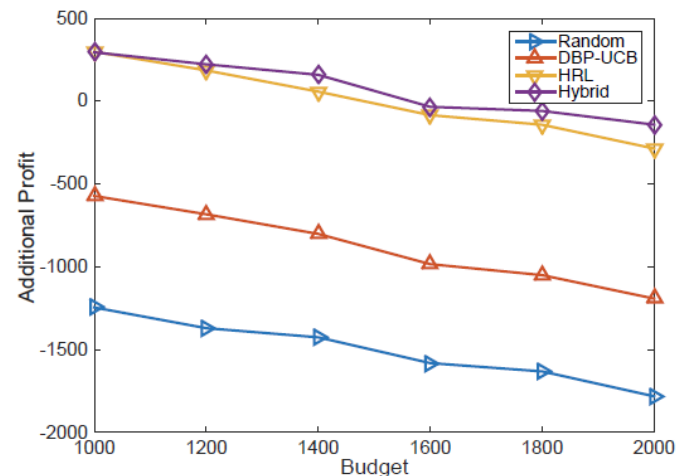
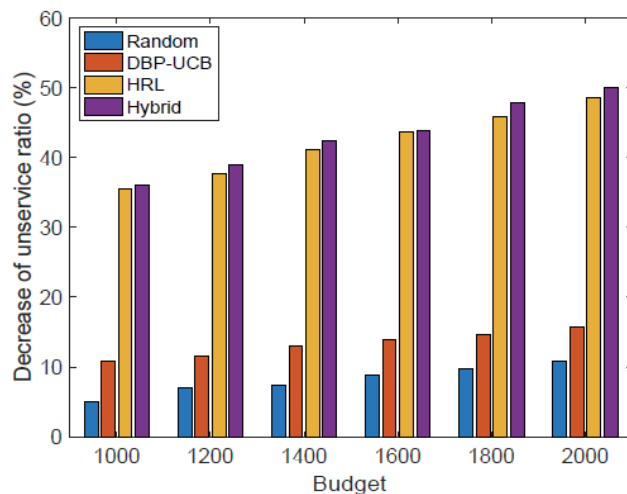
Pick-up events in 6 p.m. – 7 p.m.



Rent events distribution

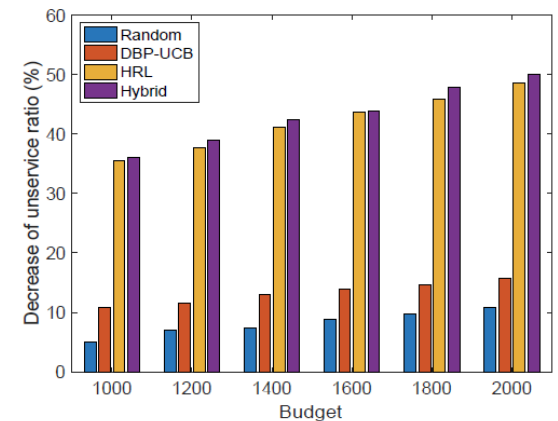
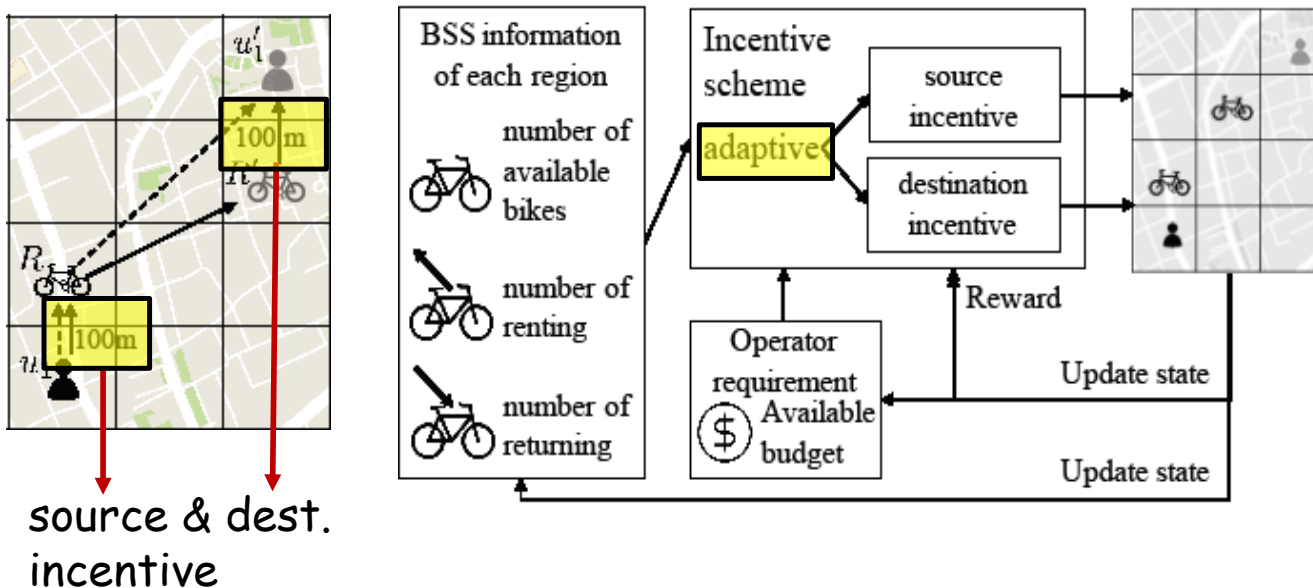
4. Simulations

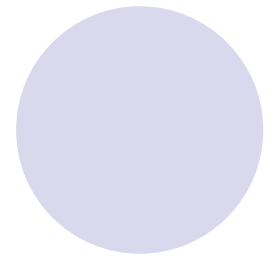
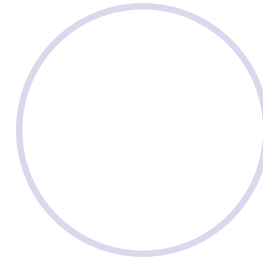
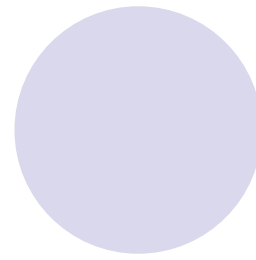
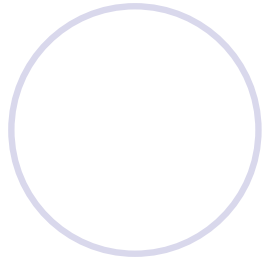
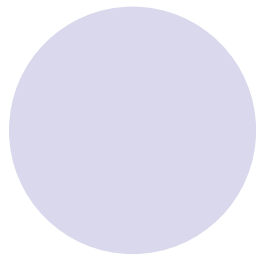
- Comparison in decreased unserved ratio (DUR)
 - $DUR = (N1 - N2) / N1$
 - N1: number of unsatisfied users **without** incentive
 - N2: number of unsatisfied users **with** incentive
 - The hybrid incentive scheme achieves the highest DUR
- Comparison in profit
 - Assume each successful ride has 1 reward
 - The Hybrid incentive scheme earns positive profit



5. Summary

- We show the advantages of destination incentives
- We propose the hybrid incentive scheme
- Experiments on the real-world dataset show the efficiency of our hybrid scheme





Thank you

Q & A

